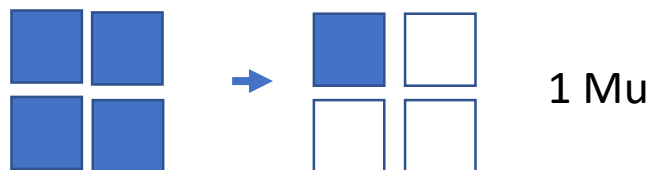


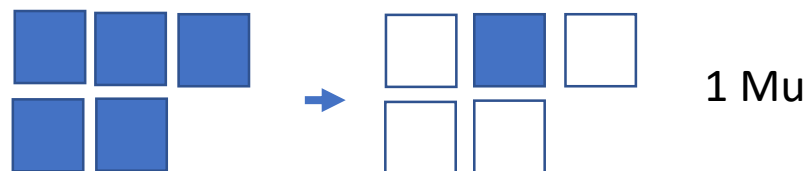
1 Tr



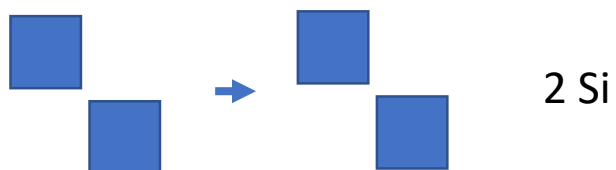
1 Tr



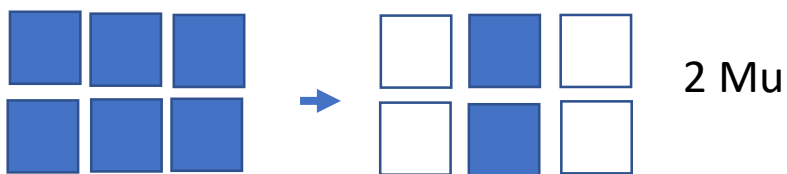
1 Mu



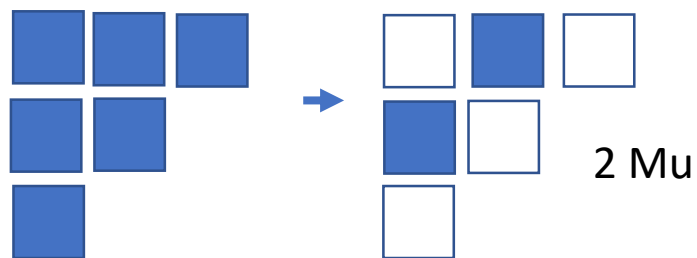
1 Mu



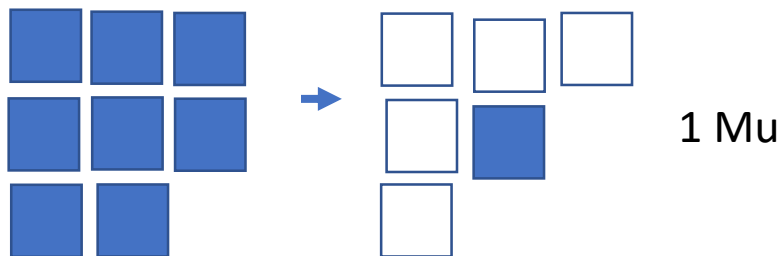
2 Si



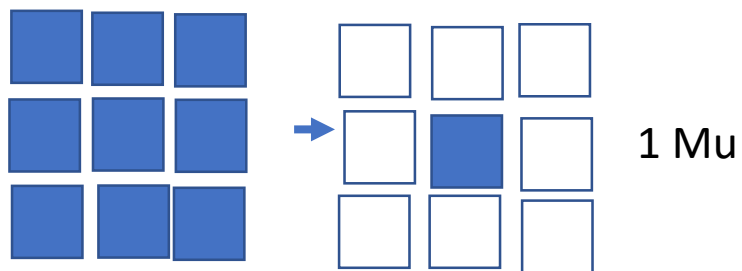
2 Mu



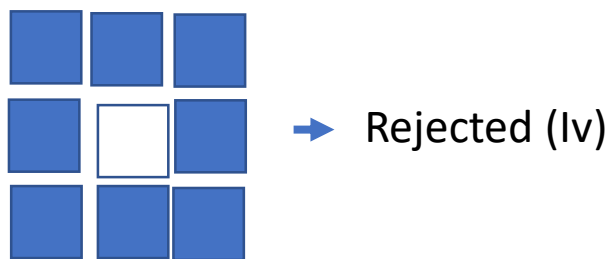
2 Mu



1 Mu



1 Mu



Rejected (lv)

The filter behaviour has been tested with simulation by activating each time a defined set of pixels.

For instance in the top left picture three adjacent pixels are set and 1 Triple event is reconstructed.

(n.b: Si stands for «single», Db four «double», Tr for «triple», Mu for «multiple». Rejected events are classified as invalid (lv)). The total amount of events detected in each category and the corresponding percentage are reported in the log file.

EX.: 69, 21, 3, 5, 3, 0 (424916319 Si, 127755654 Db, 17860054 Tr, 28200484 Mu, 19457881 lv, 0 Mh)